

L Number	Hits	Search Text	DB	Time stamp
1	7	((position\$3 or location\$1 or angle\$1 or angular) with (request\$4 near2 command\$1)) and bucket\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/27 10:19
2	53	((position\$3 or location\$1 or angle\$1 or angular) with (request\$4 near2 (command\$1 or signal\$1))) and bucket\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/27 10:31
3	90	((position\$3 or location\$1 or angle\$1 or angular) same (request\$4 near2 (command\$1 or signal\$1))) and bucket\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/27 15:44
4	25	"4982185"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/27 15:44
-	8	BRATZDRUM-E	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 11:31
-	2	BRATZDRUM-ERWIN-DIPL-ING	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 11:28
-	15	BRATZDRUM-ERWIN	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 11:30
-	2082	heidenhain.asn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 12:13
-	0	heidenhain.asn. and (linear adj bus)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 12:18
-	21	heidenhain.asn. and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 12:27
-	126	(linear near bus) and position\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 12:46
-	36	(linear near bus) and position\$3 and request\$4 and sync\$14	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 13:14
-	36	(linear near bus) and position\$3 and request\$4 and simultan\$14	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 13:19
-	325	(linear near topolog\$3) and position\$3 and request\$4 and simultan\$14	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/16 13:20

-	112	(linear near topolog\$3) and position\$3 and request\$4 and sync\$19	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 13:20
-	12	(linear near topolog\$3) and position\$3 and request\$4 and sync\$19 and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 13:28
-	14	(linear near topolog\$3) and position\$3 and request\$4 and simultan\$14 and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 13:22
-	3	(bucket adj chain\$1) and position\$3 and request\$4 and sync\$14	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 13:26
-	4	(bucket adj chain\$1) and position\$3 and request\$4 and simultan\$14	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 13:27
-	221	(bus near topolog\$3) and position\$3 and request\$4 and simultan\$19 and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 13:29
-	204	(bus near topolog\$3) and position\$3 and request\$4 and sync\$19 and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 14:18
-	18	(bus near topolog\$3) and position\$3 and (position\$4 with request\$4) and sync\$19 and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 14:52
-	18	(bus near topolog\$3) and position\$3 and (position\$4 with request\$4) and simultan\$19 and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 14:52
-	706	(702/150).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 14:56
-	88	((702/150).CCLS.) and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 15:00
-	2	((702/150).CCLS.) and ((linear near bus) or (bus near topolog\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 14:55
-	2	((702/150).CCLS.) and ((linear near bus) or ((bus or network\$1) near topolog\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 16:10
-	247	(702/151).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 14:56

-	0	((702/151).CCLS.) and ((linear near bus or ((bus or network\$1) near topolog\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/23 11:22
-	3	((702/151).CCLS.) and bus and request\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 14:57
-	21	((702/150).CCLS.) and bus and request\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 15:04
-	40	(linear near2 (bus or topolog\$4)) and bus and (position\$1 with request\$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/16 16:13
-	104	(linear near2 (bus or topolog\$4)) and bus and ((position\$1 or location\$1) same request\$6)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 15:36
-	104	(linear near2 (bus or topolog\$4)) and bus and ((position\$4 or location\$1) same request\$6) and (position\$4 or location\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 17:35
-	2	"6388906"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 13:30
-	4	"6603672"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 13:31
-	2	"20020015389"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 13:37
-	2	"20020015449"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/23 11:18
-	48	(linear near2 network\$1) and bus and ((position\$4 or location\$1) same request\$6) and (position\$4 or location\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 15:39
-	102	(linear same (bus or topolog\$4)) same bus same ((position\$4 or location\$1) same request\$6) same (position\$4 or location\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 17:01
-	102	(linear same bus) same bus same ((position\$4 or location\$1) same request\$6) same (position\$4 or location\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 17:02
-	12	((linear same bus) same bus same ((position\$4 or location\$1) same request\$6) same (position\$4 or location\$1) same (shaft\$1 or disk\$1))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/09/17 17:02

-	3330	(serial near bus) and ((position\$4 or location\$1) same request\$6) and (position\$4 or location\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 17:36
-	1644	(serial near bus) and ((position\$4 or location\$1) with request\$6) and (position\$4 or location\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 17:37
-	0	(serial near bus) and ((position\$4 or location\$1) with request\$6) and (position\$4 or location\$1) and (bucket near2 chain\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 17:38
-	3	(serial near bus) and (position\$4 or location\$1) and (bucket near2 chain\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 17:42
-	1374	(bus near2 (topolog\$3 or linear)) and (position\$3 or location\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:20
-	305	(bus near2 (topolog\$3 or linear)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 17:52
-	6	(bus near2 (topolog\$3 or linear)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and bucket\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 17:46
-	2926	((bus near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 17:53
-	2821	((bus near2 (topolog\$3 or linear)) or (linear near2 topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 17:54
-	71	((bus near2 (topolog\$3 or linear)) or (linear near2 topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1) with request\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 10:41
-	2926	((bus near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 10:28
-	610	370/\$.ccls. and ((bus near2 (topolog\$3 or linear)) or (linear with topolog\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 11:36
-	2	(mesh near2 topolog\$4) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1) with request\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 11:34
-	63	370/\$.ccls. and ((bus near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 11:05

-	9	375/\$.ccls. and ((bus near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:28
-	114	375/\$.ccls. and (point near point) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 11:18
-	162	370/\$.ccls. and (point near point) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 11:28
-	39	(702/150,151).ccls. and (point near point)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 11:57
-	4	(702/150,151).ccls. and ((bus near2 (topolog\$3 or linear)) or (linear with topolog\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 15:56
-	0	(702/152,153).ccls. and ((bus near2 (topolog\$3 or linear)) or (linear with topolog\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 12:04
-	157	(702/150,151).ccls. and serial\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 15:59
-	558	(bucket\$1 near chain\$1) and (position\$3 or location\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:21
-	18	(bucket\$1 near chain\$1) and (position\$3 or location\$1) and bus	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:21
-	9179	((bus near2 (topolog\$3 or linear)) or ethernet\$1 or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:29
-	791	((bus near2 (topolog\$3 or linear)) or ethernet\$1 or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and shaft\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:30
-	306	((bus near2 (topolog\$3 or linear)) or ethernet\$1 or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (shaft\$1 with (position\$1 or location\$1))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:30
-	1140	((bus near2 (topolog\$3 or linear)) or ethernet\$1 or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1) with request\$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:34

-	936	((bus near2 (topolog\$3 or linear)) or ethernet\$1 or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1) with request\$5) and (sync\$19 or simultan\$9)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/22 16:36
-	217	((bus near2 (topolog\$3 or linear)) or ethernet\$1 or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1) with request\$5) and ((sync\$19 or simultan\$9) with request\$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 11:59
-	2	"20030135348"	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 11:20
-	4	((702/176).CCLS.) and ((linear near bus or ((bus or network\$1) near topolog\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 11:22
-	220	(serial\$5 with transmission\$1) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1) with request\$5) and ((sync\$19 or simultan\$9) with request\$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 11:30
-	12	(serial\$5 with transmission\$1) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1) with request\$5) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 11:32
-	49	((bus near2 (topolog\$3 or linear)) or ethernet\$1 or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 12:01
-	6	((bus near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 12:03
-	6	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 12:04
-	49	((bus or mesh) near2 (topolog\$3 or linear)) or ethernet or (linear with topolog\$4)) and ((position\$3 or location\$1) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 12:34
-	14	((bus or mesh) near2 (topolog\$3 or linear)) or ethernet or (linear with topolog\$4)) and ((angle or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 12:30
-	18	(serial\$4 near (transmission or network\$1)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 12:37
-	61	(serial\$4 with (transmission or network\$1)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 15:13

-	49	ethernet and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 15:14
-	6	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:15
-	2726	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and (position\$1 with encod\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 15:41
-	204	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and (position\$1 with encod\$4) and request\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 16:18
-	1	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and (position\$1 with encod\$4) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 16:18
-	1	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and (position\$3 with encod\$4) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 16:22
-	16	(serial\$4 with (transmission or network\$1)) and (position\$3 with encod\$4) and (numerical near control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/23 16:23
-	3	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4) and ((position\$3 or location\$1 or angle\$1 or angular) with request\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:16
-	6	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4) and ((position\$3 or location\$1 or angle\$1 or angular) same request\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:17
-	6	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4) and ((position\$3 or location\$1 or angle\$1 or angular or data) same request\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:28
-	25	(serial\$4 with (transmission or network\$1)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and (numerical near control\$4) and ((position\$3 or location\$1 or angle\$1 or angular or data) same request\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:27
-	1920	(serial\$4 with (transmission or network\$1)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1 or angle\$1 or angular) same request\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:29

-	88	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1 or angle\$1 or angular) with request\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:28
-	1175	(serial\$4 with (transmission or network\$1)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1 or angle\$1 or angular) with request\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:59
-	134	((bus or mesh) near2 (topolog\$3 or linear)) or (linear with topolog\$4)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1 or angle\$1 or angular) same request\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 12:30
-	244	(serial\$4 with (transmission or network\$1)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1 or angle\$1 or angular) with request\$4 with signal\$1)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 13:04
-	132	(serial\$4 with (transmission or network\$1)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1 or angle\$1 or angular) with (request\$4 near2 signal\$1))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/24 16:37
-	67	(serial\$4 with (transmission or network\$1)) and ((position\$3 or location\$1 or angle\$1 or angular) with (measur\$9 or detect\$5 or sensor\$1 or sensing)) and ((position\$3 or location\$1 or angle\$1 or angular) with (request\$4 near2 command\$1))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/27 10:19

10677111_QUAL

5896673 99
5912096 99
4819339 99
4983826 99
5361217 99
6085600 99
4348885 98
4356556 98
4433488 98
4536809 98
4587579 98
4758959 98
4802115 98
4922281 98
4970450 98
4972326 98
5339088 98
5355526 98
5370094 98
5383128 98
5400647 98
5453941 98
5467656 98
5471406 98
5474088 98
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5678556 98
5798828 98
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5902348 98
5946160 98
5991033 98
5991115 98
5999126 98
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6078285 98
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6175328 98
6230531 98
6236832 98
4250929 98
4262306 98
4289195 98
4321683 98
4333106 98

10677111_QUAL

4350984 98
4405930 98

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PLUS Search Results for S/N 10677111, Searched September 16, 2004

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most closely related linguistically to the application searched. This search was prepared by the staff of the Scientific and Technical Information Center, SIRA.

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10677111_CLS

Most Frequently Occurring Classifications of Patents Returned
From A Search of 10677111 on September 16, 2004

Original Classifications

2 360/75
2 702/152
2 702/168

Cross-Reference Classifications

2 340/990
2 360/77.03

Combined Classifications

3 360/75
2 33/503
2 340/990
2 342/357.17
2 360/77.03
2 702/152
2 702/168

10677111 CLSTITLES

Titles of Most Frequently Occurring Classifications of Patents Returned

From A Search of 10677111 on September 16, 2004

- 3 360/75 (2 OR, 1 XR)
 - Class 360 : DYNAMIC MAGNETIC INFORMATION STORAGE OR RETRIEVAL
 - 360/69 AUTOMATIC CONTROL OF A RECORDER MECHANISM
 - 360/75 .Controlling the head
- 2 33/503 (1 OR, 1 XR)
 - Class 033 : GEOMETRICAL INSTRUMENTS
 - 33/501 GAUGE
 - 33/503 .Coordinate movable probe or machine
- 2 340/990 (0 OR, 2 XR)
 - Class 340 : COMMUNICATIONS: ELECTRICAL
 - 340/988 VEHICLE POSITION INDICATION
 - 340/989 .At remote location
 - 340/990 ..With map display
- 2 342/357.17 (1 OR, 1 XR)
 - Class 342 : COMMUNICATIONS: DIRECTIVE RADIO WAVE SYSTEMS AND DEVICES
 - 342/350 DIRECTIVE
 - 342/352 .Including a satellite
 - 342/357.01 ..With position indicating
 - 342/357.17 ...With particular action taken responsive to position
- 2 360/77.03 (0 OR, 2 XR)
 - Class 360 : DYNAMIC MAGNETIC INFORMATION STORAGE OR RETRIEVAL
 - 360/69 AUTOMATIC CONTROL OF A RECORDER MECHANISM
 - 360/75 .Controlling the head
 - 360/77.01 ..Track centering
 - 360/77.02 ...Rotary carrier
 - 360/77.03By nonmagnetic sensing (e.g., optical, capacitive)
- 2 702/152 (2 OR, 0 XR)
 - Class 702 : DATA PROCESSING: MEASURING, CALIBRATING, OR TESTING
 - 702/127 MEASUREMENT SYSTEM
 - 702/150 .Orientation or position
 - 702/152 ..3D position

10677111_CLSTITLES
2 702/168 (2 OR, 0 XR)
Class 702 : DATA PROCESSING: MEASURING, CALIBRATING, OR
TESTING
702/127 MEASUREMENT SYSTEM
702/155 .Dimensional determination
702/167 ..Contouring
702/168 ...By probe (e.g., contact)

about 1
 above 3
 absolute 2
 abstmct 1
 accompanying 1
 accomplished 1
 accordance 4
 according 3
 accordingly 4
 account 7
 achieved 1
 acquired 2
 acquisition 11
 actual 1
 additional 1
 additively 1
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make 5
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referred 2
reflection 2
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respectively 2
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resultant 2
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transmission 42
transmit 2
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two 4
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variable 1
variant 4

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well 3
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where 2
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while 3
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with 22
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words 8
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